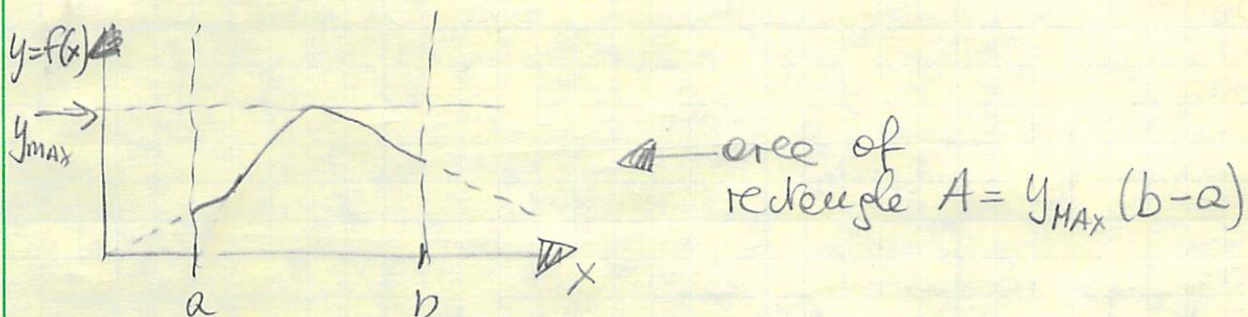


Acceptance/Rejection and MC integration



Pick N values x_i randomly btw b and a

Probability of accepting $x_i = \frac{1}{y_{\max}} f(x_i) = p(x_i)$

$n = \#$ of successes out of n

Estimate of $I = \int_a^b f(x) dx = A \cdot \frac{n}{N}$

$$\langle I \rangle = \frac{A}{N} \langle n \rangle$$

$\langle n \rangle$ will vary with random seed

$$n = \sum p(x_i) = \frac{1}{y_{\max}} \sum f(x_i)$$

$$I \sim \frac{A}{y_{\max} N} \sum_{i=1}^N f_i$$

where $f_i = f(x_i)$

$$I \sim \frac{b-a}{N} \sum_{i=1}^N f_i$$

Different random seeds will give different $\sum f_i$

How accurate is this.

We can estimate the spread in $\sum_{i=1}^N f_i$ from different seeds using a single draw.

$$\text{Variance of } f = \frac{1}{N-1} \sum_{i=1}^N [f_i - \langle f_i \rangle]^2 \equiv \sigma_f^2$$

← N terms here

Then variance of I is

$$\sigma_I^2 = \frac{(b-a)^2}{N^2} \sum_{n=1}^N \sigma_f^2$$

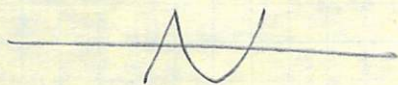
← like uncertainties in quadrature

$$\boxed{\sigma_i = \frac{b-a}{\sqrt{N}} \sigma_f}$$

Note $b-a = \int_a^b dx = \text{length of segment}$

This generalize to m -dimensional volume for m -variables. Indeed these MC methods are useful for multivariate functions

$$\text{eg } f(x_1, x_2, \dots, x_m) \Rightarrow b-a \Rightarrow V = \iiint dx_1 dx_2 dx_3 \dots dx_m$$



So far this does not look much better than splitting into little rectangles and adding up the areas —

Let's rewrite

$$I = \int_a^b f(x) dx = \int_a^b g(x) p(x) dx$$

Where $p(x)$ is the PDF over which we pick our X_i :

$$p(x) = \frac{1}{b-a} \quad g(x) = \frac{f(x)}{p(x)} = (b-a) f(x)$$

We had

$$I \sim \frac{b-a}{N} \sum_{i=1}^N f_i = \frac{1}{N} \sum g_i$$

$$\sigma_i = \frac{\sigma_g}{\sqrt{N}} \quad \text{as before}$$

How does this help us?

Remember the accuracy depends on

$$\sigma_g = \sum (g_i - \langle g_i \rangle)^2$$

i.e. the spread in g_i

Let me rewrite

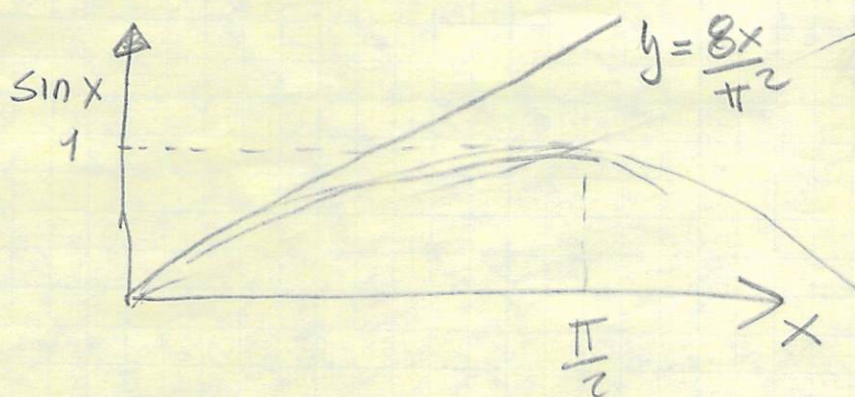
$$I = \int_a^b f(x) dx = \int_a^b \left[\frac{f(x)}{p(x)} \right] p(x) dx$$

$$g(x) = \frac{f(x)}{p(x)} \quad g_i = \frac{f_i}{P_i}$$

If I can choose $p(x)$ to be something close to $f(x)$ then the spread in the g_i will be minimized - (or up to proportionality constant)

In other words I will be sampling $f(x)$ where it is most important
Importance Sampling

Example $\int_0^{\pi/2} \sin(x) dx = 1$



Code in

/home/pi/physrpi/campagnari/testOfImportanceSampling.py