

Since  $T(a+b) = T(a)T(b)$

build  $T(a)$  by summing many  
small (infinitesimal) translations

$T(a)$  take  $a$  to be small

$$T(a) \approx T(0) + a \left. \frac{dT(a)}{da} \right|_{a=0} \quad \Leftarrow$$

operator =  $\mathbb{1}$

$$T(a) = 1 + a \left. \frac{dT(a)}{da} \right|_{a=0} \quad \text{operator}$$

$$f(x) = f(0) + x \left. \frac{df}{dx} \right|_{x=0} \quad \text{number}$$

function

$$\hat{K} = +i \left. \frac{dT(a)}{da} \right|_{a=0}$$

$$\left. \frac{dT(a)}{da} \right|_{a=0} = -i\hat{k}$$

$$T(a) = 1 - i a \hat{k}$$

$$T(-a) = 1 + i a \hat{k} = T(a)^{-1}$$

last lecture  $T(a)^{-1} = T(a)^{\dagger} = 1 + i a \hat{k}$

$$T(a)^{\dagger} = (1 - i a \hat{k})^{\dagger} = 1 + i a \hat{k}^{\dagger}$$

$\hat{k}$  is Hermitian

$$\frac{dT(a)}{da} = \lim_{\epsilon \rightarrow 0} \frac{T(a+\epsilon) - T(a)}{\epsilon}$$

$$= \lim_{\epsilon \rightarrow 0} \frac{T(a)T(\epsilon) - T(a)}{\epsilon}$$

$$= \left( \lim_{\epsilon \rightarrow 0} \left[ \frac{T(a+\epsilon) - T(a)}{\epsilon} \right] \right) T(a)$$

The limit is  $\frac{dT(a)}{da} \Big|_{a=0} = -i \hat{k}$

$$\frac{dT(a)}{da} = -i \hat{k} T(a)$$

$$T(a) = A e^{-i a \hat{k}}$$

When  $a=0$   $T(a=0) = \underline{1} \Rightarrow \underline{\underline{A=1}}$

$$T(a) = e^{-i a \hat{k}} = 1 - i a \hat{k} - \frac{1}{2} a^2 \hat{k}^2 + \dots$$

$$\hat{k} \psi = i \left( \frac{dT(a)}{da} \psi \right) \Big|_{a=0} \quad T(a) \psi(x) = \psi(x-a)$$

$$\hat{k} \psi = i \frac{d}{da} \psi(x-a) \Big|_{a=0} \quad \left( \hat{k} \right)$$

What is  $\frac{d}{da} \psi(x-a) \Big|_{a=0}$  ??

$$y = x - a \quad \frac{d}{da} = - \frac{d}{dy}$$

$$y = x - a \\ a \rightarrow 0 \\ y \rightarrow x$$

$$\Rightarrow = - \frac{d}{dy} \psi(y) \Big|_{y=x} = - \frac{d}{dx} \psi(x)$$

$$\hat{K} \psi = + i \frac{d}{da} \psi(x-a) \Big|_{a=0} = - i \frac{d}{dx} \psi$$

$$\hat{K} = - i \frac{d}{dx}$$

$$\Rightarrow \hat{K} = \frac{\hat{p}}{\hbar}$$

$$T(a) = \exp\left(-\frac{ia\hat{p}}{\hbar}\right)$$

$\frac{\hat{p}}{\hbar}$  = Generator of translations

So far we looked  $T(a)\psi(x) = \psi(x-a)$

Some other operator  $\hat{O}$

want its expectation value ...

$$\langle T\psi | \hat{O} | T\psi \rangle = \langle \psi | \underbrace{T^\dagger \hat{O} T}_{\text{transform}} | \psi \rangle$$

keep state as it was and

"transform" operator  $\hat{O} \rightarrow \underline{T^\dagger \hat{O} T}$

I imagine that  $H$  is invariant

under symm  $T^\dagger H T = H$

$$(T T^\dagger) H T = T H$$

$= 1$

$$H T = T H$$

$$[H, T] = 0$$

$$H = \frac{\hat{p}^2}{2m} + V(\vec{r})$$

If I translate by  $\vec{a}$ ,  $V(\vec{r}) \rightarrow V(\vec{r} + \vec{a})$

For  $H$  to be invariant under

translations by any  $\vec{a}$ ,  $V = \text{constant}$

CM  $V = \text{constant}$

$\Rightarrow$  1D  $F = ma = m \frac{dp}{dt}$   $F = - \frac{dV}{dx}$

$$V = \text{const}, F = 0 \Rightarrow \frac{dp}{dt} = 0$$

$\Rightarrow p$  constant

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$[H T(a)] = 0$  for any  $a$

$$T(a) = \exp\left(-i \frac{a \hat{p}}{\hbar}\right)$$

Take  $a$  to be very small

$$T(a) = 1 - i \frac{a \hat{p}}{\hbar}$$

If  $[H, \hat{O}]$  and  $\frac{d\hat{O}}{dt} = 0 \Rightarrow \langle O \rangle = \text{const}$

$$\frac{d}{dt} \langle O \rangle = \frac{d}{dt} \langle \psi | \hat{O} | \psi \rangle$$

$$= \langle \frac{d\psi}{dt} | \hat{O} | \psi \rangle + \langle \psi | \frac{d\hat{O}}{dt} | \psi \rangle + \langle \psi | \hat{O} | \frac{d\psi}{dt} \rangle$$

$$H|\psi\rangle = i\hbar \frac{d}{dt} |\psi\rangle$$

$$\frac{d}{dt} |\psi\rangle = \frac{-i}{\hbar} H|\psi\rangle$$

$$\frac{d}{dt} \langle O \rangle = \frac{1}{\hbar} \langle -iH\psi | \hat{O} | \psi \rangle + \frac{1}{\hbar} \langle \psi | \hat{O} | -iH\psi \rangle$$

$$= \frac{1}{\hbar} \langle \psi | +iH\hat{O} | \psi \rangle + \frac{1}{\hbar} \langle \psi | -iH\hat{O} | \psi \rangle$$

$$\frac{d}{dt} \langle O \rangle = \frac{i}{\hbar} \langle \psi | \underbrace{H\hat{O} - \hat{O}H}_{[H, \hat{O}]} | \psi \rangle$$



if  $[H \hat{O}] = 0$  then  $\frac{d \langle O \rangle}{dt} = 0$

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We had  $[\hat{P} H] = 0$

$\Rightarrow \frac{d \langle P \rangle}{dt} = 0$

$$[H, T(a)] = \cancel{[H, 1]} - \frac{ia}{\hbar} [H, \hat{p}] = 0$$

$= 0$

$$\Rightarrow [H, \hat{p}] = 0$$

$H$  commutes  
with generator  
of translations

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Take  $\hat{O}$ , with discrete eigenvalues

$\lambda_n$ , eigenstates  $|\phi_n\rangle$

If I am in state  $|\psi\rangle$

Prob of measuring  $\lambda_n$

$$P(\lambda_n) = (\langle \phi_n | \psi \rangle)^2$$

$$|\psi\rangle = |\psi(t)\rangle = \sum c_m e^{-\frac{iE_m t}{\hbar}} |\psi_m\rangle$$

(  
time  
independent

$$\rightarrow P(\lambda_n) = \left| \sum_m c_m e^{-\frac{iE_m t}{\hbar}} \langle \phi_n | \psi_m \rangle \right|^2$$

If  $[\hat{H}, \hat{O}] = 0$  then

eigenstates of  $\hat{O}$  and  $H$  can be made to be the same

$$|\phi_n\rangle = |\psi_n\rangle$$

$\uparrow$  eigenstates of  $O$                        $\uparrow$  eigenstates of  $H$

$$\langle \phi_n | \hat{O} | \psi_m \rangle = \lambda_m \langle \phi_n | \psi_m \rangle$$
$$\hat{O} |\phi_n\rangle = \lambda_n |\phi_n\rangle = \lambda_n \langle \psi_n | \psi_m \rangle$$
$$= \delta_{nm} \times \lambda_n$$

$$P(\lambda_n) = \left| \sum_m c_m e^{iE_m t/\hbar} \langle \phi_n | \psi_m \rangle \right|^2$$

$$= \langle \psi_n | \psi_m \rangle$$

$$= \delta_{nm}$$

$$p(\lambda_n) = |c_n|^2$$

indep  
of time