

# Physics 115B HWK 3

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$$\textcircled{1} \quad (\alpha) \quad L_+ |l m\rangle = \alpha_+(l, m) |l m+1\rangle$$

Inner product of both sides:

$$\langle l m | L_- L_+ | l m \rangle = |\alpha_+|^2 \langle l m+1 | l m+1 \rangle$$

$$\text{Since } L_- L_+ = L^2 - L_z^2 + \hbar L_z$$

$$l(l+1)\hbar^2 - \hbar^2 m^2 + \hbar^2 m = |\alpha_+|^2$$

where I also used the normalization  $\langle l m | l m \rangle = 1$  and

$$\langle l m+1 | l m+1 \rangle = 1$$

Thus, up to a phase

$$\alpha_+(l, m) = \hbar \sqrt{l(l+1) - m(m+1)}$$

Similarly taking inner products of both sides of

$$L_- |l, m\rangle = \alpha_-(l, m) |l, m-1\rangle$$

and using  $L_+ L = L^2 - L_z^2 - \hbar L_z$  we find

$$l(l+1)\hbar^2 - \hbar^2 m^2 - \hbar^2 m = |\alpha_-|^2$$

which leads to

$$\alpha_-(l, m) = \hbar \sqrt{l(l-1) - m(m-1)}$$

also up to a phase

② (a) Do it using  $\epsilon_{ijk}$  symbol

$$\text{using } L_3 = \epsilon_{ij3} x_i p_j$$

$$[L_3 x_k] = \epsilon_{ij3} x_i [p_j x_k] = -i\hbar \delta_{jk} \epsilon_{ij3} x_i$$

$$[L_3 x_k] = -i\hbar \epsilon_{ik3} x_i$$

$$k=1 \Rightarrow [L_3 x_1] = -i\hbar \epsilon_{i13} x_i = +i\hbar x_2 = +i\hbar y$$

$$k=2 \Rightarrow [L_3 x_2] = -i\hbar \epsilon_{i23} x_i = -i\hbar x_1 = -i\hbar x$$

$$k=3 \Rightarrow [L_3 x_3] = -i\hbar \epsilon_{i33} x_i = 0$$

Now the commutators with momentum

$$[L_3 p_k] = \epsilon_{ij3} [x_i p_j p_k] = \epsilon_{ij3} p_j [x_i p_k]$$

$$[L_3 p_k] = \epsilon_{ij3} p_j i\hbar \delta_{ik} = i\hbar \epsilon_{kj3} p_j$$

$$k=1 \Rightarrow [L_3 p_1] = i\hbar \epsilon_{1j3} p_j = i\hbar p_2 = i\hbar p_y$$

$$k=2 \Rightarrow [L_3 p_2] = i\hbar \epsilon_{2j3} p_j = -i\hbar p_1 = -i\hbar p_x$$

$$k=3 \Rightarrow [L_3 p_3] = i\hbar \epsilon_{3j3} p_j = 0$$

$$(b) [L_z L_x] = \begin{bmatrix} L_z & L_x \end{bmatrix} = \begin{bmatrix} L_z & yP_z - zP_y \end{bmatrix} = \\ = \begin{bmatrix} L_z & yP_z \end{bmatrix} - \begin{bmatrix} L_z & zP_y \end{bmatrix} = L_z y P_z - y P_z L_z - L_z z P_y + z P_y L_z$$

Both  $z$  and  $P_z$  commute with  $L_z$  - Thus

$$\begin{aligned} [L_z L_x] &= (L_z y - y L_z) P_z - z (L_z P_y - P_y L_z) \\ &= [L_z y] P_z - z [L_z P_y] = \\ &= -i\hbar \times P_z - z (-i\hbar P_x) \end{aligned}$$

$$[L_z L_x] = i\hbar (z P_x - x P_z) = i\hbar L_y$$

$$\begin{aligned} (c) [L_z r^2] &= [L_z x^2] + [L_z y^2] + [L_z z^2] = \\ &= [L_z x]x + x[L_z x] + y[L_z y] + [L_z y]y + z[L_z z] + [L_z z]z \\ &= i\hbar(yx + xy - yx - xy + 0 + 0) \end{aligned}$$

$$[L_z r^2] = 0$$

$$\begin{aligned} \text{Similarly } [L_z p^2] &= p_x [L_z p_x] + [L_z p_x] p_x + p_y [L_z p_y] \\ &\quad + [L_z p_y] p_y + [L_z p_z] p_z + p_z [L_z p_z] \end{aligned}$$

$$[L_z \vec{P}^2] = i\hbar (P_x P_y + P_y P_x - P_y P_x - P_x P_y + 0 + 0)$$

$$[L_z \vec{P}^2] = 0$$

③ let's look at  $\vec{L}$  component by component  
 (a)  $L_i$

$$\frac{d \langle L_i \rangle}{dt} = \frac{i}{\hbar} \langle [H L_i] \rangle$$

$$[H L_i] = \underbrace{\frac{1}{2m} [P^2 L_i]}_{\text{zero}} + [V L_i] = [V L_i]$$

↑ This is zero from the previous problem

$$[V L_i] = [V \epsilon_{ijk} X_j P_k] = \epsilon_{ijk} X_j [V P_k]$$

$$[V L_i] = +i\hbar \epsilon_{ijk} X_j \frac{\partial V}{\partial X_k} = i\hbar \underbrace{[\vec{r} \times \vec{\nabla} V]}_i$$

=  $i$ th component of  $\vec{r} \times \vec{\nabla} V$

$$\text{Thus } [\vec{V} \vec{L}] = i\hbar [\vec{F} \times \vec{\nabla} V]$$

using the definition of torque

$$[\vec{V} \vec{L}] = -i\hbar \vec{N}$$

$$\text{Since } [\vec{H} \vec{L}] = [\vec{V} \vec{L}], \quad [\vec{H} \vec{L}] = -i\hbar \vec{N}$$

$$\boxed{\frac{d\langle \vec{L} \rangle}{dt} = \frac{i}{\hbar} \langle [\vec{H} \vec{L}] \rangle = \langle \vec{N} \rangle}$$

(b) In spherical coordinates

$$\vec{\nabla} V = \frac{\partial V}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{\phi}$$

If  $V(\vec{r}) = V(r)$ , ie spherically symmetric  
 then  $\vec{\nabla} V = \frac{dV}{dr} \hat{r}$  Then  $\vec{N} = -\frac{\vec{r}}{r} \times \vec{\nabla} V = 0$