

PHYSICS 110B - WINTER 2025

MIDTERM SOLUTIONS

PROBLEM 1



$$\Phi = B x(t) b \quad \frac{d\Phi}{dt} = B b \frac{dx}{dt} = B b v(t) = -emf$$

$$I(t) = \frac{emf}{R} = - \frac{B b v(t)}{R}$$

If B is into the paper, the direction of the current is clockwise, i.e. upwards into the bar

There is a force on the moving bar which is in magnitude $F = I b B = b^2 B^2 v / R$

The direction of this force is to the left, i.e. it opposes the motion of the bar to the right

$$F = - m \frac{dv}{dt}$$

$$\frac{b^2 B^2}{R} v = - m \frac{dv}{dt}$$

Define

$$\tau = \frac{mR}{B^2 b^2}$$

$$\frac{v}{\tau} = - \frac{dv}{dt}$$

The solution, that insures $v(t=0) = v_0$ is

$$v = v_0 e^{-t/\tau}$$

PROBLEM 2

$$\vec{E} = E_0 (\hat{x} + \hat{y}) \cos \frac{2\pi}{\lambda} (z + ct)$$

This is a plane wave propagating in the negative \hat{z} direction with speed c

$$\vec{B} = \frac{1}{c} \hat{k} \times \vec{E} \quad \text{where } \hat{k} = -\hat{z}$$

$$-\hat{z} \times (\hat{x} + \hat{y}) = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0 & 0 & -1 \\ 1 & 1 & 0 \end{vmatrix} = \hat{x} - \hat{y}$$

$$\vec{B} = \frac{E_0}{c} (\hat{x} - \hat{y}) \cos \frac{2\pi}{\lambda} (z + ct)$$

PROBLEM 3

From the cheat-sheet

$$K = w \sqrt{\frac{\epsilon \mu}{2}} \left[\sqrt{1 + \left(\frac{\sigma}{\epsilon w}\right)^2} - 1 \right]^{1/2}$$

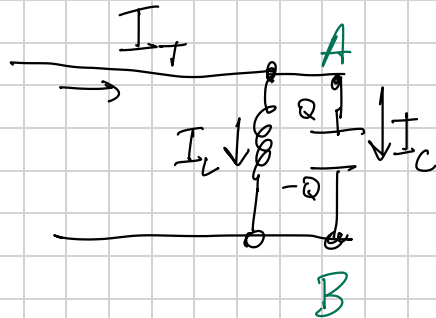
$\sigma \gg \epsilon w$ leads to

$$K \approx w \sqrt{\frac{\epsilon \mu}{2}} \left[\sqrt{\left(\frac{\sigma}{\epsilon w}\right)^2} - 1 \right]^{1/2} = w \sqrt{\frac{\epsilon \mu}{2}} \left[\frac{\sigma}{\epsilon w} - 1 \right]^{1/2}$$

$$K \approx w \sqrt{\frac{\epsilon \mu}{2}} \sqrt{\frac{\sigma}{\epsilon w}} = \sqrt{\frac{w \mu \sigma}{2}}$$

$$\text{Skin depth} = \frac{1}{K} = \sqrt{\frac{2}{w \mu \sigma}}$$

PROBLEM 4



$$I_C = \frac{dQ}{dt}$$

$$V_A - V_B = \frac{Q}{C} \quad V_A - V_B = L \frac{dI_L}{dt}$$

$$\frac{Q}{C} = L \frac{dI_L}{dt}$$

$$\frac{1}{C} \frac{dQ}{dt} = L \frac{d^2 I_L}{dt^2}$$

$$I_C = LC \frac{d^2 I_L}{dt^2}$$

$$\text{Let } \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\text{Also } I_C = I_T - I_L$$

$$I_T = \frac{1}{\omega_0^2} \frac{d^2 I_L}{dt^2} + I_L \quad (1)$$

Let's work with complex numbers.

$$\text{Try solution } I_L = \tilde{I}_{0L} e^{i\omega t}$$

$$I_0 e^{i\omega t} = -\frac{\omega^2}{\omega_0^2} \tilde{I}_{0L} e^{i\omega t} + \tilde{I}_{0L} e^{i\omega t}$$

$$\text{Gives } \tilde{I}_0 = \frac{\omega_0^2 - \omega^2}{\omega_0^2} \tilde{I}_{0L}$$

$$\tilde{I}_{0L} = \frac{\omega^2}{\omega_0^2 - \omega^2} \tilde{I}_0$$

$$I_L = \frac{\omega_0^2}{\omega_0^2 - \omega^2} I_0 e^{i\omega t}$$

$$\omega_0^2 = \frac{1}{LC}$$

And if I wanted to take the real part

$$I_L = \frac{\omega_0^2}{\omega_0^2 - \omega^2} I_0 \cos \omega t$$

I can equally well solve equation (1) without using complex numbers

Assume

$$I_L = A \cos \omega t + B \sin \omega t$$

$$\frac{d^2 I_L}{dt^2} = -\omega^2 (A \cos \omega t + B \sin \omega t)$$

Then equation (1) becomes

$$I_0 \cos \omega t = -\frac{\omega^2}{\omega_0^2} (A \cos \omega t + B \sin \omega t) + (A \cos \omega t + B \sin \omega t)$$

For this to work at all times t we need $B=0$

Then, the $\cos \omega t$ cancels, and we get

$$I_0 = -\frac{\omega^2}{\omega_0^2} A + A = \left(\frac{\omega_0^2 - \omega^2}{\omega_0^2} \right) A$$

$$A = \frac{\omega_0^2}{\omega_0^2 - \omega^2}$$

$$I_L = \frac{\omega_0^2}{\omega_0^2 - \omega^2} \cos \omega t$$

✓