

More Strongly Damped Systems

$$Q = \frac{\omega_0}{\gamma} \lesssim 10 \text{ or } 10^3!$$

$$m\ddot{z} + b\dot{z} + kz = 0 \quad z = z_0 e^{\alpha t}$$

$$\alpha = -\frac{1}{2} \frac{b}{m} \pm \sqrt{-\frac{k}{m} + \left(\frac{b}{2m}\right)^2}$$

$$\alpha = -\frac{1}{2} \gamma \pm \sqrt{-\omega_0^2 + \frac{1}{4} \gamma^2}$$

fun part...

Imagine γ getting bigger + bigger.

crucial boundary $-\omega_0^2 + \frac{1}{4} \gamma^2 = 0!$

$$\gamma = 2\omega_0$$

$$\frac{b}{m} = 2\sqrt{\frac{k}{m}}$$

"critical damping"

$$\alpha = -\frac{1}{2} \gamma$$

but $x = x_0 e^{-\frac{1}{2}\gamma t}$

↑ only one arbitrary constant

how do you handle $x(0)$, $\dot{x}(0)$?

→ there is another solution, a "remnant"

$$\left. \begin{aligned} m\ddot{z} + b\dot{z} + kz &= 0 \\ \ddot{z} + \gamma\dot{z} + \omega_0^2 z &= 0 \end{aligned} \right\} \begin{array}{l} \text{critical} \\ \gamma = 2\omega_0 \\ Q = \frac{\omega_0}{\gamma} = \frac{1}{2} \end{array}$$

$$z_1 e^{-\frac{\gamma}{2}t} \cos(\omega t)$$

$$z_2 e^{-\frac{\gamma}{2}t} \sin(\omega t)$$

↓ vanishing

↓

→ $z_1 e^{-\gamma t/2}$ is limit

$z_2 e^{-\gamma t/2} t$ is remnant

> try $z = z_2 e^{-\gamma t/2} t$

$$\dot{z} = z_2 e^{-\gamma t/2} - \frac{\gamma}{2} z_2 t e^{-\gamma t/2}$$

$$\begin{aligned} \ddot{z} &= -\frac{\gamma}{2} z_2 e^{-\gamma t/2} - \frac{\gamma}{2} z_2 e^{-\gamma t/2} + t \left(\frac{\gamma}{2}\right)^2 z_2 e^{-\gamma t/2} \\ &= -\gamma z_2 e^{-\gamma t/2} + t \left(\frac{\gamma}{2}\right)^2 z_2 e^{-\gamma t/2} \end{aligned}$$

Plug into $\ddot{z} + \gamma \dot{z} + \omega_0^2 z = 0$

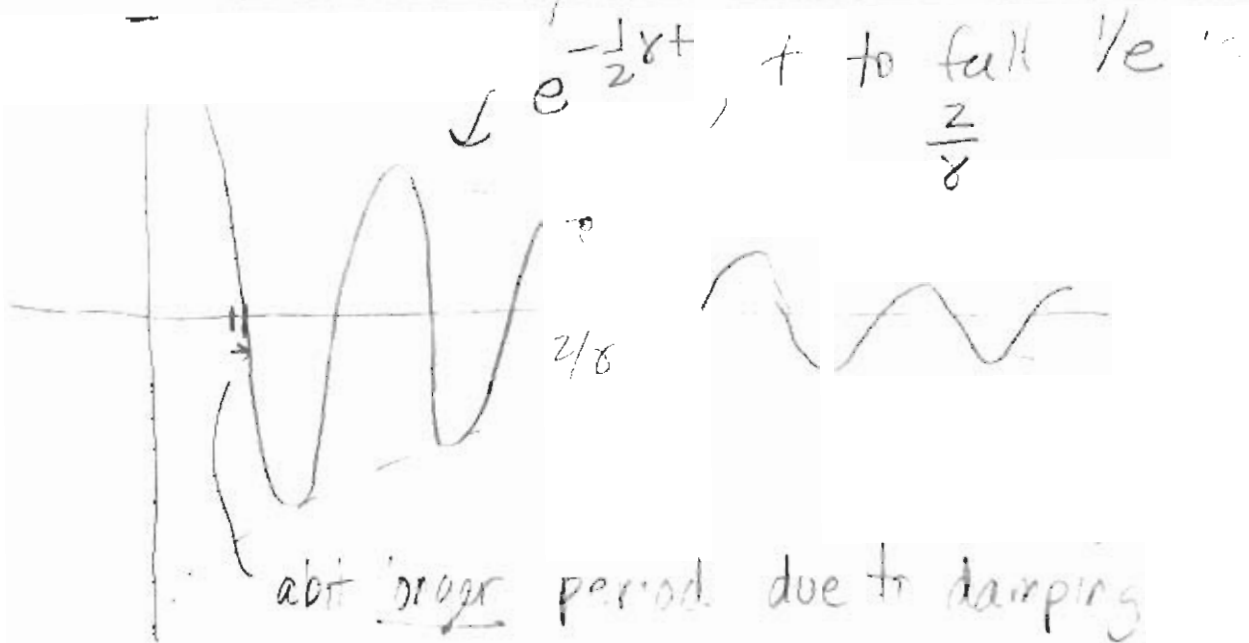
$$z_2 e^{-\gamma t/2} \left[-\gamma + \left(\frac{\gamma}{2}\right)^2 + \cancel{\gamma} - \frac{1}{2}\gamma^2 + \omega_0^2 \right] =$$

$$z_2 e^{-\gamma t/2} \left[\underbrace{\gamma^2 \left(\frac{1}{4} - \frac{1}{2} + \frac{1}{4} \right)}_0 + \right]$$

$$= 0 !$$

Overdamp

$$\alpha_{\pm} = -\frac{1}{2}\gamma \pm \sqrt{\underbrace{\left(\frac{\gamma}{2}\right)^2}_{\text{damping}} - \omega_0^2}$$



Energy in Underdamped Oscillator

$$E = \frac{1}{2} kx^2 + \frac{1}{2} m\dot{x}^2$$

$$x = A e^{-\frac{\gamma}{2}t} \cos(\omega_1 t + \phi) \quad \omega_1 = \sqrt{\omega_0^2 - \frac{1}{4}\gamma^2}$$

$$\dot{x} = -\frac{\gamma}{2} A e^{-\frac{\gamma}{2}t} \cos(\omega_1 t + \phi)$$

$$- \omega_1 A e^{-\frac{\gamma}{2}t} \sin(\omega_1 t + \phi)$$

↑
second
order

↑
a little more complicated!

$$\frac{1}{2} kx^2 = \frac{1}{2} kA^2 e^{-\gamma t} \cos^2(\omega_1 t + \phi)$$

$$\frac{1}{2} m\dot{x}^2 = \frac{1}{2} m\omega_1^2 A^2 e^{-\gamma t} \left[\sin^2(\omega_1 t + \phi) + \left(\frac{\gamma}{\omega_1}\right)^2 \sin(\omega_1 t + \phi) \cos(\omega_1 t + \phi) + \left(\frac{\gamma}{\omega_1}\right)^2 \cos^2(\omega_1 t + \phi) \right]$$