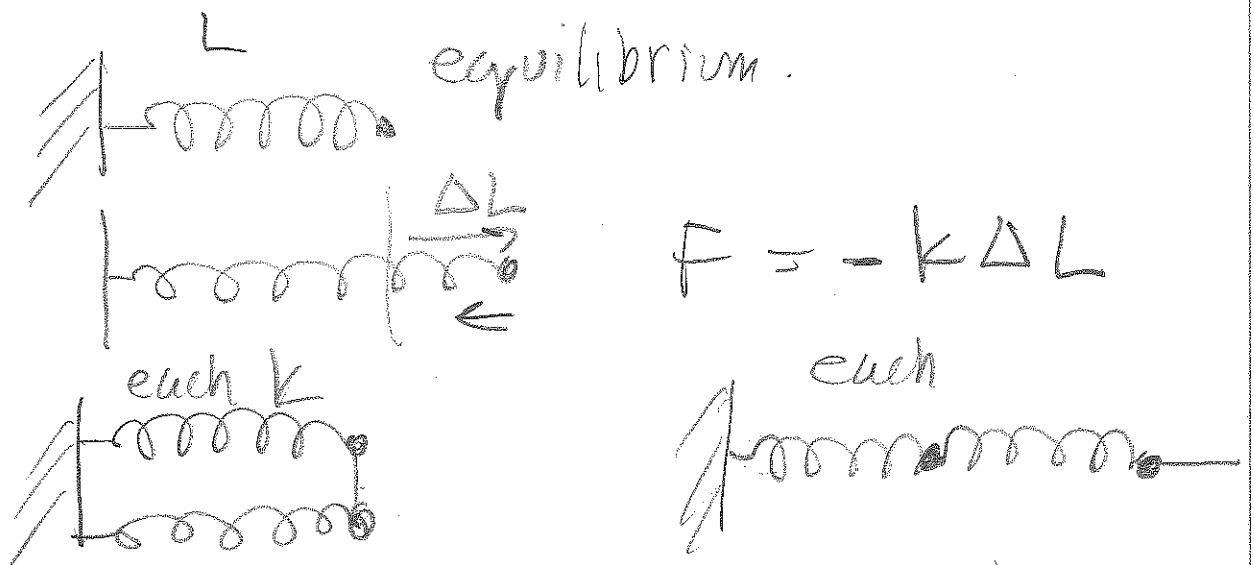


Stress (Tension / Compressive) and Strain Section 4-5
PHK4

Stress \rightarrow force / area
(like a pressure)

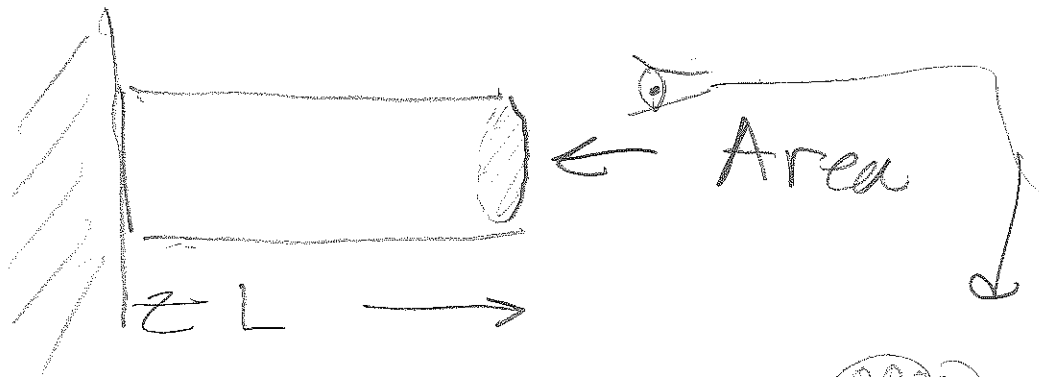
Strain $\rightarrow \Delta L / L$

Idea: ^{most} every thing, for small $\Delta L / L$, is a spring



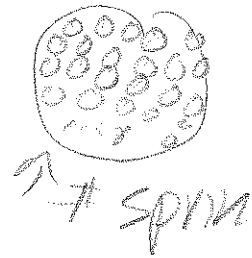
"k parallel" $\begin{matrix} A \\ B \\ C \end{matrix}$ $>$ "k series" $\begin{matrix} A \\ B \\ C \end{matrix}$
 $k_{parallel} = 2k$ $>$ $k_{series} = \frac{1}{2}k$

Slab of stuff



$$k \propto \text{Area}$$

$$k \propto \frac{1}{L}$$



$$F = - E \frac{A}{L} \Delta L$$

Young's Modulus
 N/m^2

usually written

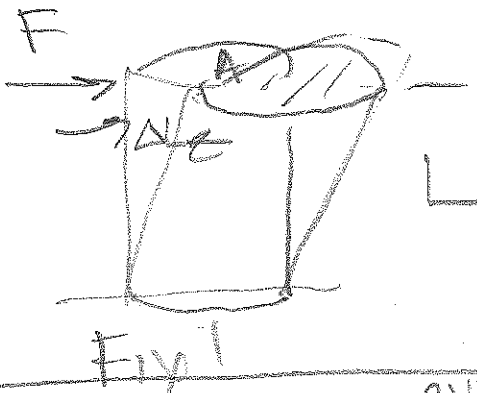
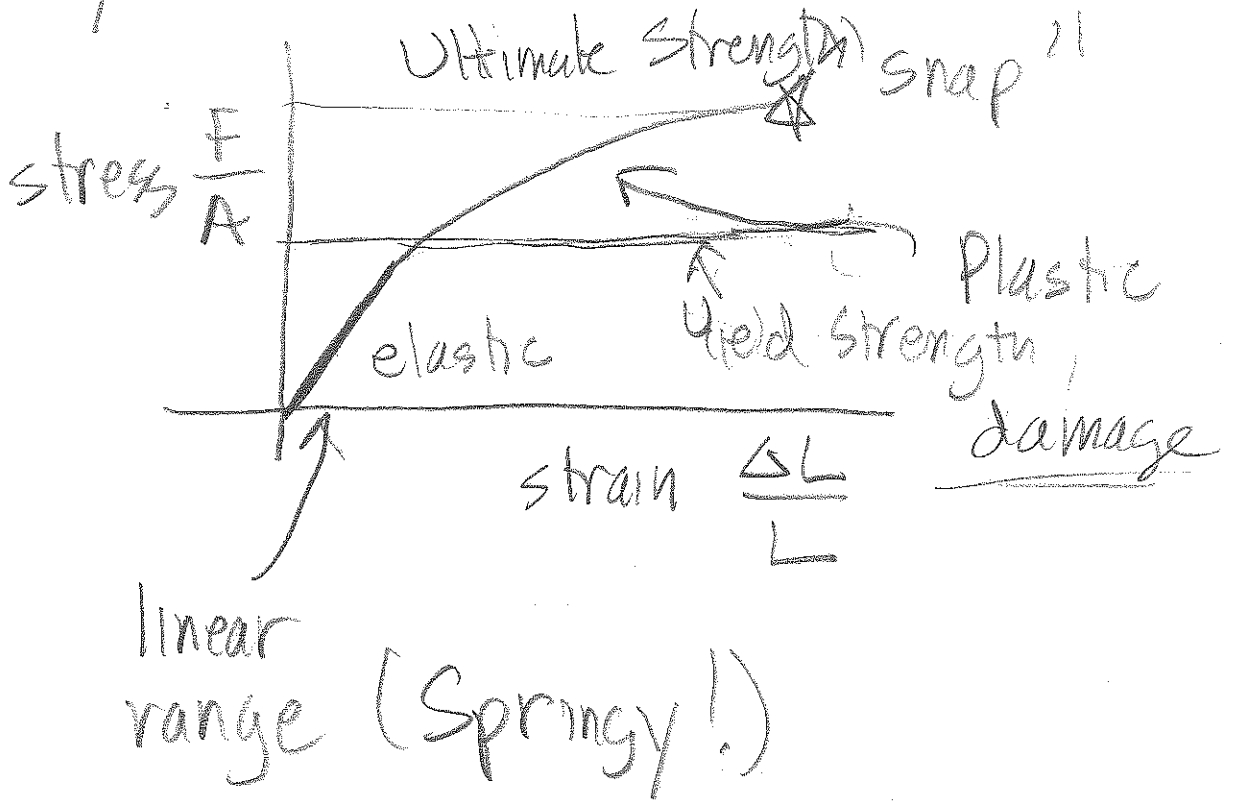
$$\left(\frac{F}{A} \right) = E \left(\frac{\Delta L}{L} \right)$$

stress $\quad \quad \quad$ strain

understood

$$E \sim 9 \cdot 10^9 \text{ N/m}^2 \text{ (bone)}$$

only an approximation -



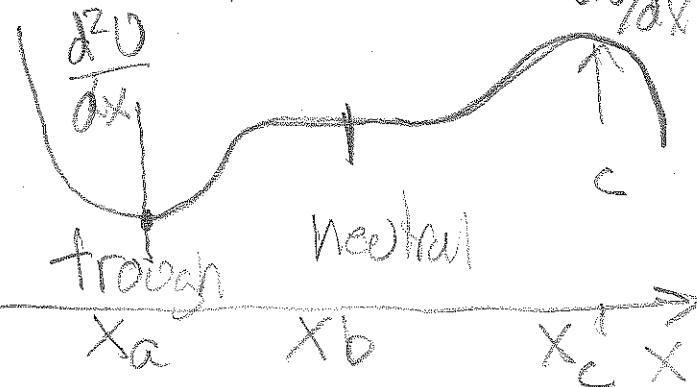
"shear"

$$\frac{F}{A} = (\text{Shear modulus}) \frac{\Delta L}{L}$$

Stability
potential
 $U(x)$

PHK4
14-4
map

$U(x)$ or $U(x,y)$



all points:

$$\frac{dU}{dx} = 0$$

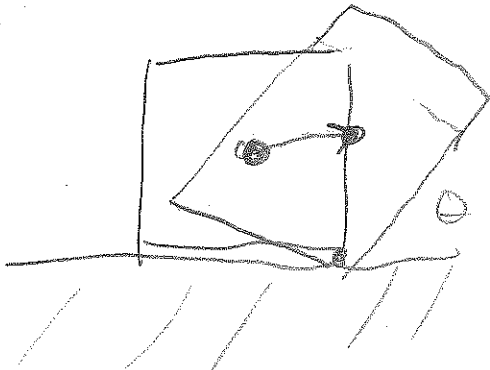
$$F = -\frac{dU}{dx} = 0$$

$$(A) \left. \frac{d^2U}{dx^2} \right|_{x_a} < 0, \quad \left. \frac{d^2U}{dx^2} \right|_{x_b} = 0, \quad \left. \frac{d^2U}{dx^2} \right|_{x_c} > 0$$

$$(B) \left. \frac{d^2U}{dx^2} \right|_{x_a} > 0, \quad \left. \frac{d^2U}{dx^2} \right|_{x_b} = 0, \quad \left. \frac{d^2U}{dx^2} \right|_{x_c} < 0$$

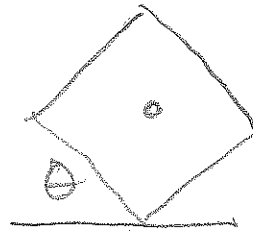
(C) Both wrong

Book / ball ... as a function of θ



cm goes up.

$$\frac{d^2U}{d\theta^2} > 0$$



$$\frac{d^2U}{d\theta^2} < 0$$



$$\frac{d^2U}{d\theta}$$

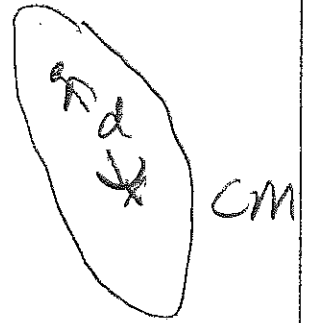
what "force" depends on θ ?

$$\frac{dU}{d\theta}$$

will be TORQUE

Physical Pendulum

$$ML^2 \rightarrow I \quad L \rightarrow d$$



$$I \ddot{\theta} \approx -Mgd\theta$$

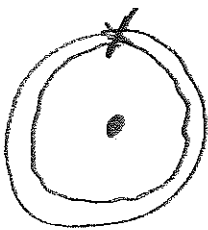
simple-

$$\omega = \sqrt{\frac{Mgd}{I}} \quad \left| \quad \sqrt{\frac{g}{L_0}}\right.$$

$$L_0 = \frac{I}{Md}$$

center of oscillation

1) Rings - = suspend on edge



$$I = MR^2 + MR^2 \\ = 2MR^2$$

$$\omega = \sqrt{\frac{MgR}{2MR^2}} = \sqrt{\frac{g}{2R}}$$

$$L_0 = \frac{2MR^2}{M \cdot R} = 2R$$

$$ML^2 \ddot{\theta} = -MgL\theta$$

$$m \ddot{x} = -kx \rightarrow \text{solution}$$
$$x_m \cos(\omega t + \phi)$$
$$x_m \sin(\omega t + \phi)$$
$$\omega = \sqrt{\frac{k}{m}}, T = 2\pi \sqrt{\frac{m}{k}}$$

$$\theta = \theta_m \cos(\omega t + \phi)$$

period $T =$

(A) Can't tell

(B) $2\pi \sqrt{\frac{M}{MgL}} = 2\pi \sqrt{\frac{L}{g}}$

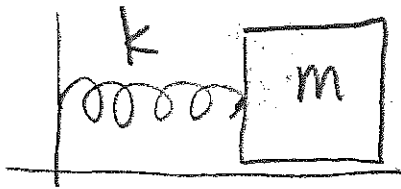
(C) $2\pi \sqrt{\frac{MgL}{ML^2}} = 2\pi \sqrt{\frac{g}{L}}$

(D) $2\pi \sqrt{g}$

(E) $2\pi \sqrt{gL}$

Simple Harmonic Motion... Note 10.1 KK

10.2 KK 15-8
10.3 KK 15-9



$$m a_x = -kx$$

$$m \frac{d^2x}{dt^2} = -kx$$

Full solution needs: initial position (x_0) and velocity (v_0)

plug in! $x(t) = X_m \cos(\omega t + \phi)$ $\omega = \sqrt{\frac{k}{m}}$

← variables

$$x_0 = x(0) = X_m \cos(\omega \cdot 0 + \phi)$$

$$\rightarrow x_0 = X_m \cos \phi$$

$$v_0 = \left. \frac{dx}{dt} \right|_{t=0} = -\omega X_m \sin(\omega t + \phi) \Big|_{t=0}$$

$$\rightarrow v_0 = -\omega X_m \sin \phi$$

Use to evaluate ϕ , x_m

$$-\frac{v_0}{\omega} = X_m \sin \phi \quad x_0 = X_m \cos \phi$$

$$\frac{X_m \sin \phi}{X_m \cos \phi} = \tan \phi = -\frac{v_0}{\omega x_0}$$

solve:

$$\phi = \tan^{-1} \left(\frac{-V_0}{\omega x_0} \right)$$

$$x_m^2 \sin^2 \phi + x_m^2 \cos^2 \phi = x_m^2 = \left(\frac{-V_0}{\omega} \right)^2 + x_0^2$$

$$x_m = \pm \sqrt{x_0^2 + \left(\frac{V_0}{\omega} \right)^2}$$

can get \nearrow from energy too!

Next: Add damping

Add driving

Need complex numbers

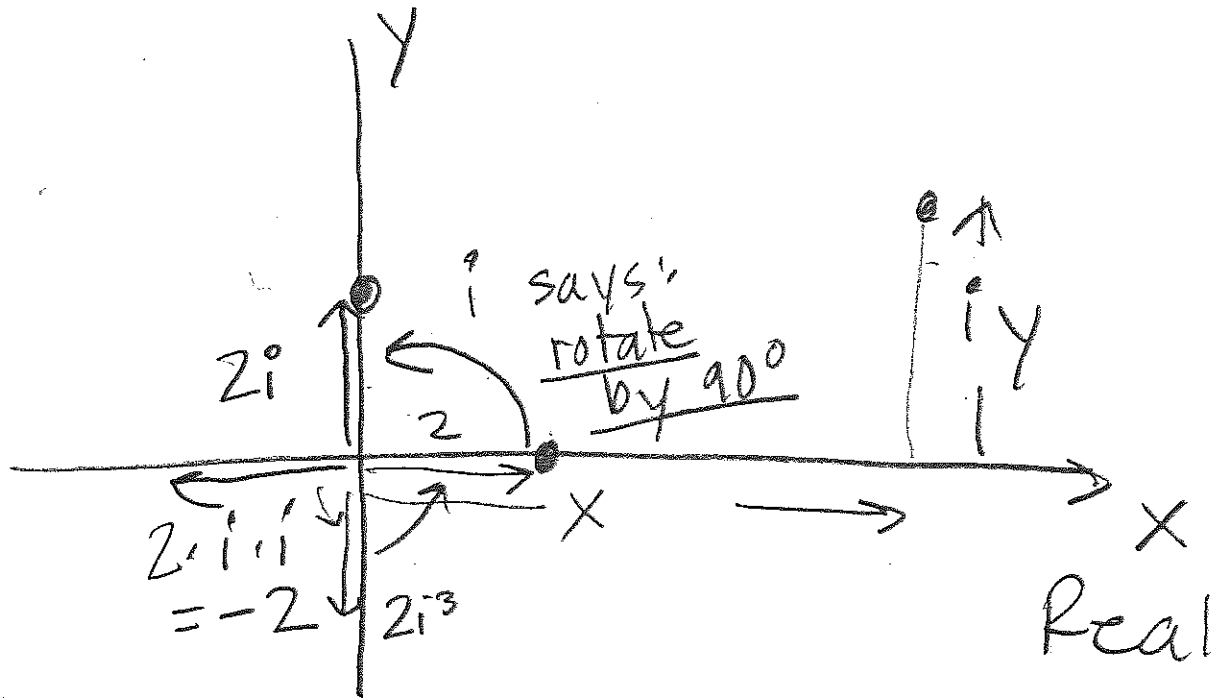
\Rightarrow K+K Note 10.1

Complex Numbers

$$\sqrt{-1} \equiv i, \text{ so, } i^2 = -1$$

Geometrically, ^{"imaginary"} i means: rotate by 90° ($\pi/2$) in the complex plane. Complex plane = Real x-axis
Imaginary y-axis.

$z = x + iy$ visualise as



So, say, $2 \cdot i$, read as:
 2 , rotated by
 90°

$$2 \cdot i \cdot i = 2 \text{ rotated twice} \\ \text{by } 90^\circ \\ = -2$$

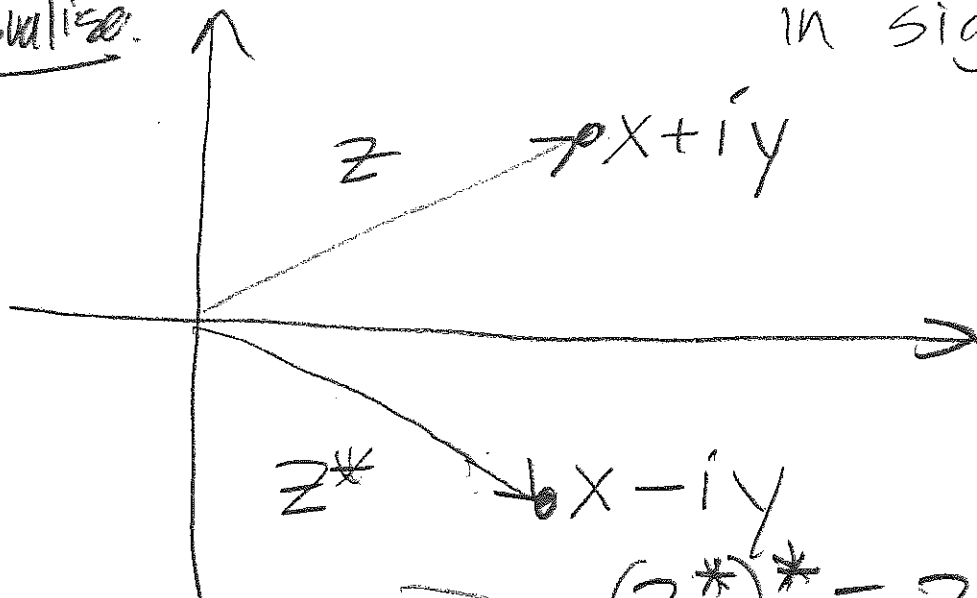
$$2 \cdot i \cdot i \cdot i = -2i$$

$$2 \cdot i \cdot i \cdot i \cdot i = 2$$

Complex Conjugation

$$z^* \equiv x - iy \quad (\text{all imaginary parts reversed in sign})$$

visualise:



$$(z^*)^* = z$$

4 properties:

$$z + z^* = 2x \equiv 2 \operatorname{Re}(z)$$

$$z - z^* = 2iy = 2i \operatorname{Im}(z)$$

$$\begin{aligned} \sqrt{z z^*} &= \sqrt{(x+iy)(x-iy)} = \sqrt{x^2 + y^2} \\ &= |z| \end{aligned}$$

$$\sqrt{\frac{z}{z^*}} = ? \quad \underline{\text{How do you divide?}}$$

$$\frac{3+4i}{2+i} \quad \underline{\underline{???}}$$

Multiply top + bottom by z^*

$$\frac{3+4i}{2+i} = \frac{(3+4i)(2-i)}{2^2+1^2} = \frac{6-3i+8i+4}{5}$$
$$= \frac{10+5i}{5} = 2+i$$

$$\frac{3+4i}{2+i} = \frac{(3+4i)(2+i)}{(2+i)(2+i)}$$
$$= \frac{6+3i+8i-4}{2^2+2i+i^2}$$
$$= \frac{2+11i}{2^2+2i+i^2}$$

(A) $\frac{3}{2} + 4 = \frac{11}{2}$

(B) $2+11i$

(C) $2+i$

(D) 5

$$\frac{z}{z^*} = \frac{z \cdot z}{z^* \cdot z} = \frac{z^2}{|z|^2}$$

magnitude is ... one!

"A PURE PHASE"