

in that case $\tilde{R}(\frac{1}{2}\pi\hat{i})$'s representation might 28
be very complicated!

Adjoint Again

$\tilde{\Omega}^+$ is... best thought of as acting on
the matrix representation:

① Take transpose (flip matrix
across diagonal)

② Take complex conjugate

if $\tilde{\Omega} = \begin{pmatrix} \Omega_{11} & \Omega_{12} & \cdots & \Omega_{1n} \\ \Omega_{21} & \Omega_{22} & & \\ \vdots & & & \\ \Omega_{n1} & & \ddots & \Omega_{nn} \end{pmatrix}$

$$\tilde{\Omega}^+ = \begin{pmatrix} \Omega_{11}^* & \Omega_{12}^* & & \Omega_{n1}^* \\ \Omega_{12}^* & \Omega_{22}^* & & \\ & & \ddots & \\ \Omega_{1n}^* & & & \Omega_{nn}^* \end{pmatrix}$$

Rotation Matrices (and operators) have
a very important property.... first...

Linear Operation = Matrix Multiplication

$\tilde{\Omega}|v\rangle$ same as:

$$\begin{pmatrix} \Omega_{11} & \Omega_{12} & \Omega_{13} & \cdots & \Omega_{1n} \\ \Omega_{21} & \Omega_{22} & & & \\ \Omega_{31} & & \ddots & & \\ \vdots & & & & \\ \Omega_{n1} & & & \ddots & \Omega_{nn} \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ \vdots \\ v_n \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n \Omega_{1i} v_i \\ \sum_{i=1}^n \Omega_{2i} v_i \\ \vdots \\ n \\ \sum_{i=1}^n \Omega_{ni} v_i \end{pmatrix}$$

$$\underbrace{A \Omega}_{\sim} |V\rangle = \begin{pmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & & \\ \vdots & \vdots & & \\ A_{n1} & \cdots & A_{nn} \end{pmatrix} \begin{pmatrix} \Omega_{11} & \Omega_{12} & \cdots & \Omega_{1n} \\ \Omega_{21} & \Omega_{22} & & \\ \vdots & \vdots & & \\ \Omega_{n1} & \cdots & \Omega_{nn} \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{pmatrix}$$

For Rotation Matrices, Their Adjoint is Their
INVERSE

Check: first representation:

$$R\left(\frac{1}{2}\pi i\right) \doteq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad R^+\left(\frac{1}{2}\pi i\right) \doteq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$R\left(\frac{1}{2}\pi i\right)R^+ \left(\frac{1}{2}\pi i\right) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$R^+(\frac{1}{2}\pi\hat{i}) R(\frac{1}{2}\pi\hat{i}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$\begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$

Unit Matrix

operators with the property

$$\underline{\Omega} \underline{\Omega}^+ = \underline{\Omega}^+ \underline{\Omega} = \underline{1}$$

called

UNITARY

Projection Operators

Identity is ... $\begin{pmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 1 & 0 & \dots & \dots \\ 0 & 0 & 1 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}$

Operators like $R_1 = \begin{pmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix}$

are very special. Note, they don't have an inverse in general. For the case above.

$$\begin{pmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix} \begin{pmatrix} 0 \\ a \\ b \\ c \\ d \end{pmatrix} = 0, \text{ so, no inverse.}$$

note, however, $R_1^2 = \begin{pmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & 0 & \dots & 0 \end{pmatrix} = R_1$

$R_1^2 = R_1$ \leftarrow key relationship; if satisfied, R_1 is a projection operator

"Acting again does no good, you get it all on the first operation!"

Recipe for a projection operator:

- 1) find a unit vector: $|w\rangle \stackrel{\text{def}}{=} \text{say, } \begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix}$
- 2) multiply $|w\rangle$ times its adjoint $|w\rangle\langle w|$

$$P_W = |W\rangle\langle W| = \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \times \begin{pmatrix} 1/2 & \sqrt{3}/2 \\ \sqrt{3}/2 & 1/2 \end{pmatrix}$$

$$= \begin{pmatrix} 1/4 & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & 3/4 \end{pmatrix}$$

3) check two ways: $P_W^2 = |W\rangle\langle W| |W\rangle\langle W| = |W\rangle\langle W|$

$$P_W^2 = P_W$$

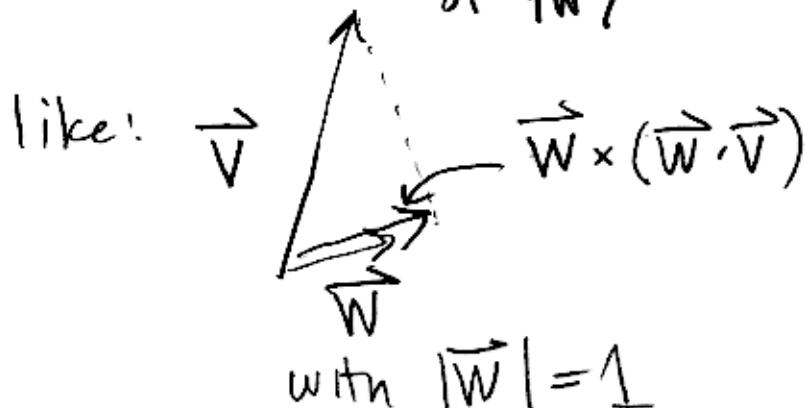
or $\begin{pmatrix} 1/4 & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & 3/4 \end{pmatrix} \begin{pmatrix} 1/4 & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & 3/4 \end{pmatrix} = \begin{pmatrix} \frac{1}{16} + \frac{3}{16} = \frac{1}{4} & \frac{\sqrt{3}}{16} + \frac{\sqrt{3} \cdot 3}{16} = \frac{1}{4}\sqrt{3} \\ \frac{\sqrt{3}}{16} + \frac{3\sqrt{3}}{16} = \frac{1}{4}\sqrt{3} & \frac{3}{16} + \frac{9}{16} = \frac{12}{16} = \frac{3}{4} \end{pmatrix}$

$$= \begin{pmatrix} 1/4 & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & 3/4 \end{pmatrix}$$

Projection Operators describe a subspace, and when they operate on a ket $|V\rangle$, they yield the component of $|V\rangle$ that lives in that subspace:

for example $P_W|V\rangle = \underbrace{|W\rangle\langle W|}_{\text{in the direction of } |W\rangle} |V\rangle$

"dot" product



"Dimension" of a Projection Operator

2 unit kets: $\langle 1|1 \rangle = \langle 2|2 \rangle = 1$

orthogonal $\langle 1|2 \rangle = \langle 2|1 \rangle = 0$

$$\rho_{12} = |1\rangle\langle 1| + |2\rangle\langle 2|$$

Is it a projection operator?

$$\rho_{12}^2 = (|1\rangle\langle 1| + |2\rangle\langle 2|)(|1\rangle\langle 1| + |2\rangle\langle 2|)$$

$$= |1\rangle\langle 1| |1\rangle\langle 1| + |1\rangle\langle 1| \overset{0}{\cancel{|2\rangle\langle 2|}} + |2\rangle\langle 2| \overset{0}{\cancel{|1\rangle\langle 1|}} + |2\rangle\langle 2| |2\rangle\langle 2|$$

$$= |1\rangle\langle 1| + |2\rangle\langle 2| \quad \checkmark \text{ yes}$$

when: $|1\rangle \doteq \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad |2\rangle \doteq \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$|1\rangle\langle 1| = \begin{pmatrix} 1 \\ 0 \end{pmatrix}(1^* 0^*) \quad |2\rangle\langle 2| = \begin{pmatrix} 0 \\ 1 \end{pmatrix}(0 1^*)$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$|1\rangle\langle 1| + |2\rangle\langle 2| \doteq \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \underset{\sim}{\cancel{1}} \quad \left(\begin{array}{l} \text{since} \\ \text{only} \\ \text{two} \\ \text{dimensions} \end{array} \right)$$

1) $\text{Tr}(\rho) =$ dimension, of relevant subspace.

2) For a basis of n kets, $|1\rangle, |2\rangle, \dots, |n\rangle$
when $\sum_{i=1}^n |i\rangle\langle i| = \underset{\sim}{\cancel{1}}$ we say the basis
is complete, "completeness"

3) Operator: $\underline{\underline{\Omega}}$

$$\underline{\underline{\Omega}} = \begin{pmatrix} \Omega_{11} & \Omega_{12} & \cdots & \Omega_{1n} \\ \Omega_{21} & \Omega_{22} & \cdots & \vdots \\ \vdots & \vdots & \ddots & \Omega_{nn} \\ \Omega_{n1} & \Omega_{n2} & \cdots & \Omega_{nn} \end{pmatrix}$$

in some basis
 $|i\rangle$

$$\underline{\underline{\Omega}} = \sum_{ij} |i\rangle \Omega_{ij} \langle j|$$

then $\langle k | \underline{\underline{\Omega}} | l \rangle = \sum_{ij} \langle k | i \rangle \Omega_{ij} \langle j | l \rangle$

↑
pick k, l ↑
 δ_{ki} ↑
 δ_{jl}

$$\langle k | \underline{\underline{\Omega}} | l \rangle = \Omega_{kl}$$

aka $\Omega_{ij} = \langle i | \underline{\underline{\Omega}} | j \rangle$

4) Matrix Multiplication:

$$(\underline{\underline{\Omega}} \underline{\underline{\Lambda}})_{ij} = \langle i | \underline{\underline{\Omega}} \underline{\underline{\Lambda}} | j \rangle$$

$$\langle i | \underline{\underline{\Omega}} \underline{\underline{\Lambda}} | j \rangle$$

$$\sum_{k=1}^n |k\rangle \langle k|$$

$$= \langle i | \underline{\underline{\Omega}} \sum_{k=1}^n |k\rangle \langle k| \underline{\underline{\Lambda}} |j \rangle$$

$$= \sum_{k=1}^n \langle i | \underline{\underline{\Omega}} | k \rangle \langle k | \underline{\underline{\Lambda}} | j \rangle = \sum_k \Omega_{ik} \Lambda_{kj}$$

Adjoints

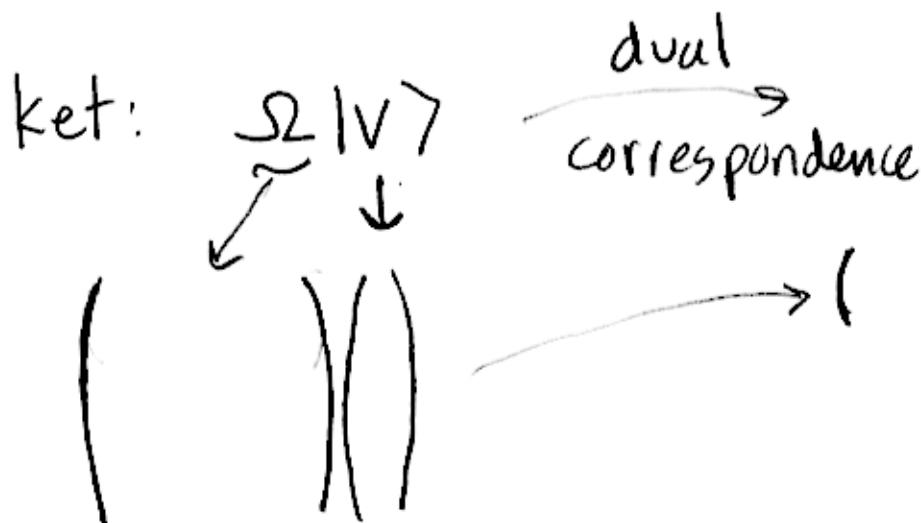
$$\underline{\Omega} = \begin{pmatrix} \Omega_{11} & \Omega_{12} & \dots & \Omega_{1n} \\ \Omega_{21} & \Omega_{22} & & \\ \vdots & \vdots & & \\ \Omega_{n1} & \Omega_{n2} & \dots & \Omega_{nn} \end{pmatrix} \quad \underline{\Omega}^+ = \begin{pmatrix} \Omega_{11}^* & \Omega_{21}^* & \dots & \Omega_{n1}^* \\ \Omega_{12}^* & \Omega_{22}^* & & \\ \vdots & \vdots & & \\ \Omega_{n2}^* & \Omega_{nn}^* & \dots & \Omega_{nn}^* \end{pmatrix}$$

$$\Omega_{ij}^+ = \Omega_{ji}^*$$

other ways:

$$\underline{\Omega} = \sum_{ij} |i\rangle \underline{\Omega}_{ij} \langle j| \quad \langle k|\underline{\Omega}|l\rangle = \Omega_{kl}$$

$$\underline{\Omega}^+ = \sum_{ij} |j\rangle \underline{\Omega}_{ij}^* \langle i| \quad \langle k|\underline{\Omega}^+|l\rangle = \Omega_{lk}^*$$



$$\underline{\Lambda} \underline{\Omega} |v\rangle \longrightarrow \langle v| \underline{\Omega}^+ \underline{\Lambda}^+$$

$$\text{so } (\underline{\Lambda} \underline{\Omega})^+ = \underline{\Omega}^+ \underline{\Lambda}^+$$

Hermitian Operators

Comparison Table:

<u>Complex Numbers</u> α, β	<u>Operators</u> \tilde{L}, \tilde{A}
• commute: $\alpha\beta = \beta\alpha$	• don't always commute $\tilde{A}\tilde{L} \neq \tilde{L}\tilde{A}$ sometimes
• <u>real</u> when: $\alpha = \alpha^*$	• <u>Hermitian</u> when $\tilde{L} = \tilde{L}^+$
• <u>imaginary</u> when: $\alpha = -\alpha^*$	• <u>Anti-Hermitian</u> when $\tilde{L} = -\tilde{L}^+$
• <u>unit magnitude</u> $\alpha \cdot \alpha^* = \alpha^* \alpha = 1$	• <u>Unitary</u> when $\tilde{L}\tilde{L}^+ = \mathbb{1} = \tilde{L}^+\tilde{L}$
• Any complex number α : $\alpha = \frac{1}{2}(\alpha + \alpha^*) + \frac{1}{2}(\alpha - \alpha^*)$ <div style="display: flex; justify-content: space-around; align-items: center;"> Real Imaginary </div>	• Any operator \tilde{L} : $\tilde{L} = \frac{1}{2}(\tilde{L} + \tilde{L}^+) + \frac{1}{2}(\tilde{L} - \tilde{L}^+)$ <div style="display: flex; justify-content: space-around; align-items: center;"> Hermitian anti-Hermitian </div>

Unitary Transformations

$$\tilde{U}\tilde{U}^+ = \tilde{U}^+\tilde{U} = \mathbb{1}$$

columns are unit vectors

saying:

$$\begin{pmatrix} U_{11}^* & U_{21}^* & \dots & U_{n1}^* \\ U_{12}^* & U_{22}^* & \dots & U_{n2}^* \\ \vdots & \vdots & \ddots & \vdots \\ U_{1n}^* & U_{2n}^* & \dots & U_{nn}^* \end{pmatrix} \begin{pmatrix} U_{11} & U_{12} & U_{13} & \dots & U_{1n} \\ U_{21} & U_{22} & U_{23} & \dots & U_{2n} \\ U_{31} & U_{32} & U_{33} & \dots & U_{3n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ U_{n1} & U_{n2} & U_{n3} & \dots & U_{nn} \end{pmatrix} = \begin{pmatrix} 1 & 0 & & & \\ 0 & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ & & & & \ddots \end{pmatrix}$$

0's mean they are orthogonal.